

黎曼几何

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Chapter 1

黎曼度量

1 定义和例子

2 Riemannian metric

$$\gamma : (a, b) \rightarrow M$$

$$\int_a^b |\gamma'(t)| dt = \text{length}(\gamma)$$

Hilbert space \implies Riemannian geometry

Banach space \implies Finsler geometry

Just for the purpose of

$$\gamma'(t), (v, x)$$

$$\|\gamma'(t)\|^2 = g_{ij} v^i v^j = (v^1, \dots, v^d) \begin{pmatrix} g_{11} & & \\ & \ddots & \\ & & g_{dd} \end{pmatrix} \begin{pmatrix} v^1 \\ \vdots \\ v^d \end{pmatrix} \text{ bilinear form, } (g_{ij}) \text{ positive definite, symmetric}$$

matrix

$$(U, y) \quad w^i \frac{\partial}{\partial y^i} = w^i \frac{\partial x^j}{\partial y^i} \frac{\partial}{\partial x^j}$$

$$h_{ij}(y(p)) = g_{kl}(x(p)) \frac{\partial x^k}{\partial y^i} \frac{\partial x^l}{\partial y^j}$$

(g_{ij}) $(0, 2)$ tensor! And we assume its coefficients are smooth on $x(U)$

定义 2.1. A Riemannian metric g on a smooth manifold M is a smooth $(0, 2)$ -tensor satisfying

$$g(X, Y) = g(Y, X), \quad g(X, X) \geq 0 \text{ \& } g_p(X, X) = 0 \iff X(p) = 0$$

for any smooth tangent vector field X, Y .

A Riemannian manifold is a smooth manifold with a Riemannian metric.

例子 2.2. \mathbb{R}^n

- $(g_{ij}) = (\delta_{ij})$
- 球面几何 $(g_{ij}) = \frac{4}{(1 + \sum_{i=1}^n (x^i)^2)^2} (\delta_{ij})$
- 双曲几何 $(g_{ij}) = \frac{4}{(1 - \sum_{i=1}^n (x^i)^2)^2} (\delta_{ij})$

2.1 Existence of Riemannian metric

定理 2.3. *A smooth manifold has a Riemannian metric.*

Extrinsic proof. Whitney embedding

$f : M^n \rightarrow N^{n+k}$ smooth immersion (df_p is injective)

Let (N, g_N) be a Riemannian metric

Pull-back metric f^*g_N on M

$$(f^*g_N)_p(X_p, Y_p) = g_N(df_p(X_p), df_p(Y_p))$$

□

Intrinsic proof. U_p coordinate neighborhood. $\{U_p, p \in M\}$ open cover.

paracompact \implies WLOG, let $\{U_\alpha\}$ be a locally finite covering of M by coordinate neighborhood.

Partition of unity $\{\varphi_\alpha\}$ subordinate to $\{U_\alpha\}$.

$x : U_\alpha \rightarrow x(U_\alpha) \subset \mathbb{R}^n$

$$g_p(X, Y) = \sum_{\alpha} \varphi_\alpha(p)(g_\alpha)_p(X, Y).$$

□

定义 2.4. *Let $(M, g_M), (N, g_N)$ be two Riemannian manifolds. $\varphi : M \rightarrow N$ is called an **isometry** if φ is a diffeomorphism and $\varphi^*g_N = g_M$.*

2.2 黎曼度量张量 \rightsquigarrow 度量

定义 2.5. A function $d: M \times M \rightarrow \mathbb{R}$ is called a metric if

- (i) $d(p, q) \geq 0$, and $d(p, q) = 0 \iff p = q$.
- (ii) $d(p, q) = d(q, p)$.
- (iii) $d(p, q) \leq d(p, r) + d(r, q)$, $\forall r \in M$.

Let (M, g) be a Riemannian manifold, for any $p, q \in M$, consider

$C_{p,q} = \{\gamma: [a, b] \rightarrow M \mid \gamma \text{ piecewise smooth regular curve with } \gamma(a) = p, \gamma(b) = q\}$.

Define $d(p, q) = \inf \{Length(\gamma) \mid \gamma \in C_{p,q}\}$.

The following questions are immediate

- (1) Is $C_{p,q}$ empty?
- (2) Is $d(p, q) < +\infty$?
- (3) Is d a metric?
- (4) Can the infimum be attained?

Let $E_p = \{q \in M \mid p, q \text{ can be connected by a curve } \in C_{p,q}\}$. It is easy to show by connectedness argument that $E_p = M$. So $C_{p,q}$ could not be empty.

Take $\gamma \in C_{p,q}$, we can cover it by finite coordinate charts. So we just need to show any piecewise smooth curve contained in a coordinate chart has finite length.

$$Length(\gamma) = \int_a^b \sqrt{g_{ij} \frac{\partial x^i \circ \gamma}{\partial t} \frac{\partial x^j \circ \gamma}{\partial t}} dt$$

引理 2.6.

Next we show $d(p, q)$ is a metric. It is obvious from definition that $d(p, q) \geq 0$ and $d(p, q) = d(q, p)$. Because we consider piecewise smooth curve, triangle inequality is also easy. If $p \neq q$, we can find a coordinate chart U of p such that $q \notin U$.

2.3 度量 \rightsquigarrow 黎曼度量张量

<https://mathoverflow.net/questions/45154/riemannian-metric-induced-by-a-metric>

3 黎曼体积形式

4 商流形的黎曼度量

1

2

Chapter 2

寻找最短线

定义 0.1. 设 $c: [a, b] \rightarrow M$ 是一条光滑曲线. c 的一个 (单参数) 变分是指一个光滑映射

$$F: [a, b] \times (-\varepsilon, \varepsilon) \rightarrow M, \quad (t, s) \mapsto F(t, s)$$

满足 $F(t, 0) = c(t)$. 记 $\frac{\partial F}{\partial t} = dF \left(\frac{\partial}{\partial t} \right)$, $\frac{\partial F}{\partial s} = dF \left(\frac{\partial}{\partial s} \right)$ (注意该记法与将 $dc \left(\frac{d}{dt} \right)$ 记作 $c'(t)$ 的习惯相同). 称沿 c 的向量场 $V(t) := \frac{\partial F}{\partial s}(t, 0)$ 为变分场.

1 例子

Euclidean geometry

$$(r, \theta)$$

$$g = dr \otimes dr + r^2 d\theta \otimes d\theta$$

$$\gamma: [a, b] \rightarrow M, \gamma(a) = p, \gamma(b) = q$$

$$Length(\gamma) = \int_a^b \sqrt{g(\gamma'(t), \gamma'(t))} dt$$

$$(r(t), \theta(t)), r'(t) \frac{\partial}{\partial t} + \theta'(t) \frac{\partial}{\partial \theta}$$

$$\begin{aligned} Length(\gamma) &= \int_a^b \sqrt{g(\gamma'(t), \gamma'(t))} dt \\ &= \int_a^b \sqrt{r'(t)^2 + r(t)^2 \theta'(t)^2} dt \\ &\geq \int_a^b |r'(t)| dt \\ &\geq \left| \int_a^b r'(t) dt \right| \\ &= |r(b) - r(a)| \end{aligned}$$

= holds iff $\theta'(t) \equiv 0$, $\gamma(t)$ monotonic.

$$S^2 \subset \mathbb{R}^3$$

$$\begin{aligned} & \varphi \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right), \theta \in (0, 2\pi) \\ & \left\{(\varphi, \theta) \mid \varphi \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right), \theta \in (0, 2\pi)\right\} \\ & g = d\varphi \otimes d\varphi + \cos^2 \varphi d\theta \otimes d\theta \end{aligned}$$

2 弧长泛函与能量泛函

设 (M, g) 是一个黎曼流形.

定义 2.1. 称光滑曲线 $\gamma: [a, b] \rightarrow M$ 是正则的如果 $\|\gamma'(t)\| \neq 0, \forall t \in I$.

分段光滑 (正则) 曲线

定义 2.2. If $\gamma: I \rightarrow M$ is a smooth regular curve and if $p: I' \rightarrow I$ is a smooth map with non-zero derivative, then we say that $\gamma \circ p: I' \rightarrow M$ is a reparametrization of $\gamma: I \rightarrow M$.

It is easy to check that any reparametrization of a smooth regular curve is still a smooth regular curve and this defines an equivalent relationship on the space of all smooth regular curves to M .

We will use **parametrized curve** to refer to a smooth regular curve and **curve without parametrization** to refer to an equivalent class of smooth regular curves under reparametrization.

Let $\gamma: [a, b] \rightarrow M$ be a parametrized curve, we can define its length

$$L(\gamma) = \int_a^b \|\gamma'(t)\| dt := \int_a^b \sqrt{g(\gamma'(t), \gamma'(t))} dt.$$

It is easy to check that

引理 2.3. If $\gamma \circ p: I' \rightarrow M$ is a reparametrization of $\gamma: I \rightarrow M$, then $L(\gamma \circ p) = L(\gamma)$.

So we can actually define length for curves without parametrization.

弧长参数化

There is always a canonical representative element for any equivalent class of smooth regular curves under reparametrization.

命题 2.4. Suppose $\gamma: I \rightarrow M$ is a parametrized curve.

(1) $p: I \rightarrow [0, L(\gamma)], t \mapsto \int_a^t \|\gamma'(s)\| ds$ is a smooth map with non-zero derivative.

(2) Suppose $\gamma \sim \gamma'$, then $\gamma \circ p^{-1} = \gamma' \circ p'^{-1}$ as maps from $[0, L(\gamma)]$ to M .

We call $\gamma \circ p^{-1}$ the **arclength reparametrization** of γ .

命题 2.5. $\gamma: I \rightarrow M$ is parametrized with arclength iff $\|\gamma'(t)\| \equiv 1$.

能量泛函

定义 2.6. 设 $\gamma: [a, b] \rightarrow M$ 是分段光滑正则曲线, 定义

$$E(\gamma) = \frac{1}{2} \int_a^b \langle \gamma'(t), \gamma'(t) \rangle dt$$

3 能量泛函的变分 I

设 (M, g) 是一个黎曼流形. 设 $\gamma: [a, b] \rightarrow M$ 是一条光滑曲线, F 是 γ 的一个变分.

任给 $y(t)$ 满足 $y(a) = y(b) = 0$,

$$\begin{aligned}
2E(\gamma_\varepsilon) &= \int_a^b g_{ij}(x(t) + \varepsilon y(t)) \frac{d}{dt}(x^i(t) + \varepsilon y^i(t)) \frac{d}{dt}(x^j(t) + \varepsilon y^j(t)) dt \\
0 &= \frac{d}{d\varepsilon} \Big|_{\varepsilon=0} 2E(\gamma_\varepsilon) = \int_a^b g_{ij,k}(x) y^k \frac{dx^i}{dt} \frac{dx^j}{dt} dt + \int_a^b g_{ij}(x) \frac{dy^i}{dt} \frac{dx^j}{dt} dt + \int_a^b g_{ij}(x) \frac{dx^i}{dt} \frac{dy^j}{dt} dt \\
&\int_a^b g_{ij}(x) \frac{dx^i}{dt} \frac{dy^j}{dt} dt = - \int_a^b \frac{d}{dt} \left(g_{ij}(x) \frac{dx^i}{dt} \right) y^j dt = - \int_a^b g_{ij,k}(x) \frac{dx^k}{dt} \frac{dx^i}{dt} y^j dt - \int_a^b g_{ij}(x) \frac{d^2 x^i}{dt^2} y^j dt \\
&\int_a^b g_{ij}(x) \frac{dy^i}{dt} \frac{dx^j}{dt} dt = - \int_a^b \frac{d}{dt} \left(g_{ij}(x) \frac{dx^j}{dt} \right) y^i dt = - \int_a^b g_{ij,k}(x) \frac{dx^k}{dt} \frac{dx^j}{dt} y^i dt - \int_a^b g_{ij}(x) \frac{d^2 x^j}{dt^2} y^i dt \\
0 &= \int_a^b \left(g_{ij,k}(x) \frac{dx^i}{dt} \frac{dx^j}{dt} - g_{ik,j}(x) \frac{dx^j}{dt} \frac{dx^i}{dt} - g_{kj,i}(x) \frac{dx^i}{dt} \frac{dx^j}{dt} - 2g_{ik}(x) \frac{d^2 x^i}{dt^2} \right) y^k dt \\
&g_{ij,k}(x) \frac{dx^i}{dt} \frac{dx^j}{dt} - g_{ik,j}(x) \frac{dx^j}{dt} \frac{dx^i}{dt} - g_{kj,i}(x) \frac{dx^i}{dt} \frac{dx^j}{dt} - 2g_{ik}(x) \frac{d^2 x^i}{dt^2} \\
&2g_{lk}(x) \frac{d^2 x^l}{dt^2} + (g_{ik,j} + g_{kj,i} - g_{ij,k}) \frac{dx^i}{dt} \frac{dx^j}{dt} = 0 \\
&\frac{d^2 x^l}{dt^2} + \frac{1}{2} g^{kl} (g_{ik,j} + g_{kj,i} - g_{ij,k}) \frac{dx^i}{dt} \frac{dx^j}{dt} = 0
\end{aligned}$$

定义 3.1. 设 (M, g) 是黎曼流形, (U, x) 是一个坐标卡, g 在 (U, x) 下的分量表示为 (g_{ij}) , 定义 U 上的一族函数 $\Gamma_{ij}^k = \frac{1}{2} g^{kl} (g_{jl,i} + g_{il,j} - g_{ij,l})$, 称作第二类 Christoffel 符号.

命题 3.2.

$$(1) \Gamma_{ij}^k = \Gamma_{ji}^k$$

$$(2) g_{ij,l} = g_{kj} \Gamma_{il}^k + g_{ik} \Gamma_{jl}^k$$

命题 3.3. $\tilde{\Gamma}_{ij}^k = \Gamma_{\alpha\eta}^\gamma \frac{\partial x^\alpha}{\partial \tilde{x}^i} \frac{\partial x^\eta}{\partial \tilde{x}^j} \frac{\partial \tilde{x}^k}{\partial x^\gamma} + \frac{\partial \tilde{x}^k}{\partial x^\gamma} \frac{\partial^2 x^\gamma}{\partial \tilde{x}^i \partial \tilde{x}^j}$

命题 3.4. $\frac{d^2 x^k}{dt^2} + \Gamma_{ij}^k \frac{dx^i}{dt} \frac{dx^j}{dt} = 0$ 是定义在流形上的方程.

定义 3.5. A parametrized curve $\gamma: [a, b] \rightarrow M$ satisfies the equation above is called a geodesic.

命题 3.6. Geodesics are parametrized proportionally by arclength

证明.

$$\begin{aligned}
\frac{d}{dt} \left(g_{ij}(x(t)) \frac{dx^i(t)}{dt} \frac{dx^j(t)}{dt} \right) &= g_{ij,l} \frac{dx^l}{dt} \frac{dx^i}{dt} \frac{dx^j}{dt} + 2g_{ij} \frac{d^2 x^i}{dt^2} \frac{dx^j}{dt} \\
&= g_{ij,l} \frac{dx^l}{dt} \frac{dx^i}{dt} \frac{dx^j}{dt} + 2g_{ij} \left(-\Gamma_{kl}^i \frac{dx^k}{dt} \frac{dx^l}{dt} \right) \frac{dx^j}{dt} \\
&= (g_{ij,l} - 2g_{kj} \Gamma_{il}^k) \frac{dx^l}{dt} \frac{dx^i}{dt} \frac{dx^j}{dt}
\end{aligned}$$

Claim $g_{ij,l} = g_{kj} \Gamma_{il}^k + g_{ik} \Gamma_{jl}^k$

$$RHS = \frac{1}{2} g_{kj} g^{kp} (g_{pl,i} + g_{ip,l} - g_{il,p}) + \frac{1}{2} g_{ik} g^{kp} (g_{pl,j} + g_{jp,l} - g_{jl,p})$$

$$= \frac{1}{2}(g_{il,i} + g_{ij,l} - g_{il,j}) + \frac{1}{2}(g_{il,j} + g_{ji,l} - g_{jl,i}) = g_{ij,l}$$

□

定理 3.7. $\forall p \in M, \exists \mathcal{U}_{V,\delta} = \{(q, v) \mid p, q \in V \subset M \text{ open } v \in T_q M, \|v\| < \delta, \delta > 0\}$

and a $\varepsilon > 0$ and C^∞ map $\gamma : (-\varepsilon, \varepsilon) \times \mathcal{U}_{V,\delta} \rightarrow M$ s.t. $\forall (q, v) \in \mathcal{U}_{V,\delta}$, the curve $t \mapsto \gamma(t, q, v)$ is the unique geodesic satisfying $r(0, q, v) = q, r'(0, q, v) = v \in T_q M$

3 月 4 日 22 分 27 秒

引理 3.8 (Homogeneity of geodesic). *If the geodesic $\gamma(t, q, v)$ is defined on $t \in (-\varepsilon, \varepsilon)$, then the geodesic $\gamma(t, q, \lambda v), \lambda \in \mathbb{R}^+$ is defined on the interval $t \in (-\frac{\varepsilon}{\lambda}, \frac{\varepsilon}{\lambda})$ and*

$$\gamma(t, q, \lambda v) = \gamma(\lambda t, q, v).$$

废稿

Consider the length functional $L: C_{p,q} \rightarrow \mathbb{R}$.

我要找 L 的最小值点. 一个简单但关键的观察是: 如果 γ 是连接 p 和 q 的最短线, 那么它也是连接其上 p, q 之间任意两点的最短线. 因此我们可以将问题局部化!

下一个观察是, 作为 L 的我要找 L 的最小值点, 首先找 L 的极小值点.

假设 $\gamma_0 \in C_{p,q}$ 是 L 的极小值点, 那么对于任意一族曲线 $\gamma_\varepsilon: (-\delta, \delta) \rightarrow C(p, q)$, 都应有

$$\left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} L(\gamma_\varepsilon) = 0, \quad \left. \frac{d^2}{d\varepsilon^2} \right|_{\varepsilon=0} L(\gamma_\varepsilon) \geq 0.$$

注记. γ_ε 上得附加可微性吧? 不然 $L(\gamma_\varepsilon)$ 怎么可导?

Localizable

Suppose γ is the shortest curve connecting p and q , then it is also the shortest curve connecting any two points on γ between p and q . WLOG, we can suppose p, q are in one coordinate chart.

注记. 但这里是不是还需要说明我们不需要考虑那些跑出 p, q 落在的坐标卡的那些曲线, 只考虑包含在坐标卡里的那些曲线.

Energy functional

$$L(\gamma_\varepsilon) = \int_a^b \sqrt{g_{ij}(x \circ \gamma_\varepsilon(t)) \frac{dx^i \circ \gamma_\varepsilon(t)}{dt} \frac{dx^j \circ \gamma_\varepsilon(t)}{dt}} dt$$

要对它求导太麻烦, 为此我们考虑能量泛函 $E(\gamma) = \frac{1}{2} \int_a^b g(\gamma'(t), \gamma'(t)) dt$.

引理 3.9. $\forall \gamma \in C_{p,q}, \gamma: [a, b] \rightarrow M$, we have

$$L(\gamma)^2 \leq 2(b-a)E(\gamma).$$

and “=” holds iff $\|\gamma'(t)\| \equiv \text{const}$.

证明.

$$L(\gamma) = \int_a^b \|\gamma'(t)\| dt \leq \left(\int_a^b 1^2 dt \right)^{\frac{1}{2}} \left(\int_a^b \|\gamma'(t)\|^2 dt \right)^{\frac{1}{2}} = \sqrt{b-a} \sqrt{2E(\gamma)}.$$

□

容易验证 $E(\gamma)$ 只能对于参数化曲线 $\gamma: [a, b] \rightarrow M$ 定义, 这与长度泛函是不同的.

If γ is arclength parametrized, then $L(\gamma)^2 = 2L(\gamma) \cdot E(\gamma) \implies L(\gamma) = 2E(\gamma)$.

Let us fix some notations. Suppose

$$\begin{aligned} \gamma: [a, b] &\longrightarrow U \subset M^n \xrightarrow{x} x(U) \subset \mathbb{R}^n \\ t &\longmapsto \gamma(t) \in U \longmapsto x(\gamma(t)) =: x(t) \end{aligned}$$

where $\gamma: [a, b] \rightarrow M$ is a parametrized curve and (U, x) is a chart.

Given $y: [a, b] \rightarrow \mathbb{R}^n$ a parametrized curve such that $y(a) = y(b) = 0$, define $\gamma_\varepsilon(t) = x(t) + \varepsilon y(t)$.

You can believe that for sufficient small δ , γ_ε is contained in $x(U)$, $\forall \varepsilon \in (-\delta, \delta)$.

注记. 一个问题是这样构造出来的 γ_ε 是否把所有的这种扰动找全了.

注记. 流形上没有线性结构, 搬到 \mathbb{R}^n 上去加!

命题 3.10 (光滑 + 最短线 + 平行弧长参数 \implies 能量泛函临界点). *If γ is a C^∞ shortest curve from p to q . (前一句话与参数化无关, 但后一句话给定了一个参数化) Then γ with a parametrization $\gamma: [a, b] \rightarrow U \subset M$ s.t. $\|\gamma'(t)\| \equiv \text{const}$ is a critical point of E , i.e., $\frac{d}{d\varepsilon} \Big|_{\varepsilon=0} E(\gamma_\varepsilon) = 0$.*

注记.

- 原则上来说最短线是在所有分段光滑的曲线中找的, 以后会说明最短线一定是光滑的.
- 在不担心这个额外的光滑性假定的条件下, 上面的命题告诉我们, 最短线赋予平行于弧长的参数一定是能量泛函的临界点.

因此如果我们去找能量泛函的临界点, 是不会漏掉最短线的.

证明. γ shortest $\implies L(\gamma) \leq L(\gamma_\varepsilon)$

$$\begin{aligned} L(\gamma) &= \sqrt{2(b-a)E(\gamma)} \\ L(\gamma_\varepsilon) &\leq \sqrt{2(b-a)E(\gamma_\varepsilon)} \\ \implies E(\gamma) &\leq E(\gamma_\varepsilon) \\ \implies \frac{d}{d\varepsilon} \Big|_{\varepsilon=0} E(\gamma_\varepsilon) &= 0. \end{aligned}$$

□

最短线加弧长参数是临界点, 临界点如果都不是弧长参数就完了, 没听懂.

4 指数映射

要根据一点附近的测地线的性质，来确定一个坐标系，使得测地线在这个坐标映射下投到欧氏区域后是直线。

其实拿切空间来做坐标区域应该是个挺自然的想法，毕竟切空间是该处的一阶线性近似

$$\begin{aligned}\exp_p : T_p M &\longrightarrow M \\ v &\longmapsto \gamma(1, p, v)\end{aligned}$$

- 选取 1 能够使测地线走的长度等于 $\|v\|_g$.

指数映射的定义域

3 月 4 日 52 分 30 秒

$V_p := \{v \in T_p M \mid \text{the geodesic } \gamma(t, p, v) \text{ is defined on } [0, 1]\}$.

为了 \exp_p 成为坐标映射，我们希望 V_p 至少包含以 O 为心的一个开球！

3 月 4 日 55 分 45 秒

命题 4.1.

(1) V_p is star-shaped around $O \in T_p M$, i.e. $\forall v \in V_p, \forall \lambda \in [0, 1]$, then $\lambda v \in V_p$.

(2) $\forall p, \exists \varepsilon = \varepsilon(p)$, s.t. $\gamma(t, p, v)$ is defined on $[0, 1]$ once $\|v\| < \varepsilon$.

3 月 4 日 1 小时 1 分 0 秒，反函数定理

3 月 4 日 1 小时 5 分 2 秒

命题 4.2. $d\exp_p = \text{Id}_{T_p M}$.

由逆映射定理，存在 p 点的一个邻域 U 使得 $\exp_p^{-1}: U \rightarrow T_p M$ 是微分同胚。

距离 \exp_p^{-1} 成为坐标映射只差 $T_p M$ 到 \mathbb{R}^n 的一个同构，任取 $T_p M$ 的一组基即可。

命题 4.3. $\Gamma_{ij}^k(p) = 0$.

命题 4.4. 选取 $T_p M$ 的一组基 $\{v_1, \dots, v_n\}$. 断言 g 在坐标映射 $\exp_p^{-1}: U \rightarrow T_p M \cong \mathbb{R}^n$ 下的分量在 O 处的取值 $g_{ij}(O) = g(v_i, v_j)$.

定义 4.5. 选取 $T_p M$ 的一组标准正交基，此时的 (\exp_p^{-1}, U) 称为 p 的一个法坐标。

3 月 4 日 1 小时 17 分 45 秒

证明. $0 = \frac{d^2 x^i}{dt^2} + \Gamma_{jk}^i(x(t)) \frac{dx^j}{dt} \frac{dx^k}{dt}$

□

极坐标

$$\begin{aligned}
 & \text{A curve } c(t) = (r(t), \varphi^1(t), \dots, \varphi^{n-1}(t)) \\
 & c'(t) = \left(\frac{dr}{dt}, \frac{d\varphi^1}{dt}, \dots, \frac{d\varphi^{n-1}}{dt} \right) =: (v^1, v^2, \dots, v^n) \\
 & \|c'(t)\| = g_{ij}(c(t))v^i v^j = \left(\frac{dr}{dt} \right)^2 + \underbrace{\sum_{i,j=1}^{n-1} g_{\varphi^i \varphi^j} \frac{d\varphi^i}{dt} \frac{d\varphi^j}{dt}}_{\geq 0}
 \end{aligned}$$

3月8日第二段 11分20秒

推论 4.6. For any $p \in M, \exists \rho > 0$ s.t. $\forall q$ with $d(p, q) = \rho$, there exists a unique shortest curve $\in C_{p,q}$.

证明. $\exists \rho > 0$ s.t. $B(p, 2\rho)$ lies in a Riemannian polar coordinate neighborhood.

For any curve $c \in C_{p,q}$

$$c : [0, T] \rightarrow M, c(0) = p, c(T) = q$$

□

推论 4.7. 最短线是光滑的.

5 一致邻域

3月8日 25分20秒

3月8日 28分56秒

定义 5.1. *totally normal neighborhood.*

$\forall p \in M$, if $W \ni p$, W is a normal neighborhood of every point $q \in W$, then W is called a **totally normal neighborhood**.

5.1 totally normal neighborhood 的存在性

3月8日第二段 35分4秒

引理 5.2.

$$d \exp(p, 0_p) : T_{p,0_p}(TM) \longrightarrow T_{p,p}(M \times M)$$

is non singular.

3月8日第二段 1小时3分54秒

定理 5.3. *For any $p \in M$, \exists a neighborhood W of p , and a $\delta > 0$ such that $\forall q \in W$, \exp_q is a diffeomorphism on $B(0_q, \delta) \subset T_qM$ and*

3月8日第二段 1小时14分7秒

推论 5.4.

6 Cut locus 1

3月8日第二段 1 小时 25 分 32 秒, 总结

测地线的最大存在区间的端点是开的

3月8日第二段 1 小时 28 分 5 秒

给定 $p \in M, v \in T_p M$, 有测地线 $\gamma(t, p, v) = \exp_p tv$.

假设 $[0, b]$ 是 γ 的最大存在区间. 记 $q = \gamma(b, p, v), w = \left. \frac{d}{dt} \right|_{t=b} \gamma(t, p, v)$.

存在经过 q , 以 w 为初始切向量的测地线 $\tilde{\gamma}$, $\tilde{\gamma}$ 在某区间 $(-\varepsilon, \varepsilon)$ 上有定义.

断言 $\gamma|_{(b-\varepsilon, b]}$ 的反转与 $\tilde{\gamma}|_{(-\varepsilon, 0]}$ 的反转都是以 q 为起点, 以 $-w$ 为初始切向量的测地线.

这是由链式法则与测地线方程的特点保证的.

由存在唯一性知 γ 与 $\tilde{\gamma}$ 在公共定义域上重合. 这与 $[0, b]$ 是 γ 的最大存在区间矛盾.

测地线是最短线的最大区间相对测地线的最大存在区间是闭的

3月8日第二段 1 小时 31 分 7 秒

由最短线也是连接其上任意两点的最短线, 知测地线是最短线的点是个区间.

$A = \{t > 0 \mid d(p, \gamma(t)) = t\|v\|_g\}$ 是闭的.

Either $A = (0, b)$ or $A = (0, a]$ for some $0 < a < b$.

定义 6.1.

- 如果 $A = (0, a]$, 则称 $\gamma(a)$ 是 p 沿测地线 γ 的割点.
- 如果 $A = (0, b)$, 则称 p 沿测地线 γ 没有割点.
- 称割点的全体为 p 的割迹, 记作 $C(p)$.
- 定义 $\tau: \{v \in T_p M \mid \|v\|_g = 1\} \rightarrow \mathbb{R}, \tau(v) = \begin{cases} a & \text{if } \exp_p(av) \text{ is a cut point of } p \\ b & \text{if } p \text{ has no cut point along } t \mapsto \exp_p(tv) \end{cases}$

定义 6.2.

- Define a map $\tau: S_p \rightarrow \mathbb{R} \cup \{\infty\}$
- $$\forall v \in S_p, \tau(v) = \begin{cases} a & \text{if } \exp_p(av) \text{ is a cut point of } p \\ \infty & \text{if } p \text{ has no cut point along } t \mapsto \exp_p(tv) \end{cases}$$
- $$E(p) = \{tv \mid v \in S_p, 0 \leq t < \tau(v)\}$$
- $$\tilde{C}(p) = \{tv \mid v \in S_p, t = \tau(v)\}$$
- $$C(p) = \{\text{cut points of } p\} = \exp_p(\tilde{C}(p))$$

$[0, b)$ is the maximal interval on which $t \mapsto \exp_p tv$ is defined.

命题 6.3. $\forall p, q \in M, \exists$ two shortest curve connecting p and q ,

推论 6.4. $\exp_p: E(p) \rightarrow \exp_p(E(p)) \subset M$ is injective.

证明. Suppose $\exists V, W \in E(p)$ s.t. $\exp_p(V) = \exp_p(W) = q$.

$$t \mapsto \exp_p\left(t \frac{v}{\|v\|}\right)$$

$$t \mapsto \exp_p\left(t \frac{w}{\|w\|}\right)$$

Contradiction. □

推论 6.5. $\exp_p(E(p)) \cap C(p) = \emptyset$.

证明. Suppose $\exists v \in \tilde{C}(p), W \in E(p)$ s.t. $\exp_p V = \exp_p W = q$

Contradiction. □

Question: $\exp_p(E(p)) \cup C(p) = M?$

$$\mathbb{R}^2 \setminus \{0\}$$

$$\forall q \in \exp_p(E_p) \cup C(p) = M?$$

7 Hopf-Rinow Theorem

3月11日 27分14秒

任给 $p_0, q \in M, d(p_0, q) = r_0$. 我们想要找 p_0, q 之间的最短线.

我们知道局部上总是可以做的, 问题是 p_0, q 可能离得很远.

思路是一步一步走.

选取以 p_0 为中心的一个 normal ball $B(p_0, \rho_0)$, 若 $q \in B(p_0, \rho_0)$, 结束.

若 $q \notin B(p_0, \rho_0)$, 假设 p_0, q 之间存在最短线 γ , 易知

- $\gamma \cap \partial B(p_0, \rho_0) = \{pt\} =: \{p_1\}$.

- $d(p_0, q) = \min_{p \in \partial B(p_0, \rho_0)} d(p, q)$.

从 p_1 出发, 我们可以找一个 normal ball $B(p_1, \rho_1)$, 并重复上述操作.

问题是: (1) p_0 到 p_2 的分段曲线是最短的吗? (2) 最终能达到 q 吗?

- $d(p_1, q) = r_0 - \rho_0$

- 假如 $d(p_1, q) < r_0 - \rho_0$, 那么可以找到一条连接 p_0, q 的长度小于 r_0 的曲线, 矛盾.

- 假如 $d(p_1, q) > r_0 - \rho_0$. 任选连接 p_0, q 的曲线 γ , $Length(\gamma) \geq \rho_0 + d(p_1, q)$.

取下确界, 得 $r_0 \geq \rho_0 + d(p_1, q) > r_0$, 矛盾.

- $d(p_0, p_2) = \rho_0 + \rho_1$

- $d(p_0, p_2) \leq d(p_0, p_1) + d(p_1, p_2) = \rho_0 + \rho_1$.

- $d(p_0, p_2) \geq d(p_0, q) - d(p_2, q) = r - (r - \rho_0 - \rho_1) = \rho_0 + \rho_1$.

因此, 走了 n 步之后, p_0 和 p_n 之间的连线仍是最短的.

3月11日 55分24秒名场面: 方向决定道路, 道路决定命运.

容易举出一些例子使得 (2) 不成立, 为此我们附加一些额外的条件.

3月11日 59分19秒

定义 7.1.

- *injective radius at $p \in M$* : $i(p) = \sup \left\{ \rho > 0 \mid \exp_p \Big|_{B(0, \rho)} \text{ is a diffeomorphism} \right\}$.

- *injective radius of M* : $i(M) = \inf_{p \in M} i(p)$.

$$M \text{ compact} \implies i(M) > 0.$$

3月11日 1小时4分52秒

Given $p \in M$,

1. Assumption I: $\overline{B_p(r)}$ is compact (\iff All closed bounded subsets of M is compact).
2. Assumption II: (M, g) is a complete metric space.
3. Assumption III: $\exp_p(p)$ is defined on the whole space $T_p M$.

这三个条件都可以保证 (2). 下面用 Assupmtion III 推 (2).

3 月 21 日 1 小时 11 分 43 秒

证明. $p, V \in T_p M$ $c(t) = \exp_p tV$

Aim: $c(r) = \exp_p(rV) = q$

Consider the set $I := \{t \in [0, r] \mid d(c(t), q) = r - t\}$

□

1 小时 24 分 33 秒

事实上, 上面几种假定是等价的, 这就是 Hopf-Rinow 定理.

3 月 15 日 2 分 31 秒

定理 7.2 (Hopf-Rinow, 1931). *Let (M, g) be a Riemannian manifold, TFAE*

- (1) (M, d_g) is a complete metric space.
- (2) All closed bounded subsets of M is compact.
- (3) $\exists p \in M$, \exp_p is defined on the whole $T_p M$.
- (4) $\forall p \in M$, \exp_p is defined on the whole $T_p M$.

Moreover, each of the statements (1) – (4) implies

- (5) $\forall p, q \in M$ can be joined by a shortest curve.

注记. 原始论文: *Ueber den Begriff der vollständigen differentialgeometrischen Fläche.*

证明.

- (3) \implies (2)

Claim: $\forall r > 0, \overline{B(p, r)}$ is compact.

For any bounded closed subset K , $\exists r_k$ such that $K \subset \overline{B(p, r_k)}$.

FACT: $\overline{B(p, r)} = \exp_p(\overline{B(O_p, r)})$

– $\exp_p(\overline{B(O_p, r)}) \subset \overline{B(p, r)}$

$\forall v \in \overline{B(O_p, r)}, d(p, \exp_p V) \leq r \implies \exp_p V \in \overline{B(p, r)}$

– $\forall q \in \overline{B(p, r)},$

- (2) \implies (1)

- (1) \implies (4)

Suppose $\exists p \in M$ and $v \in T_p M$ such that the geodesic $t \mapsto \exp_p tv$ is defined on the maximal interval $[a, b), b < \infty$.

For any $\{t_n\} \subset [a, b)$ such that $t_n \rightarrow b$, $d(\exp_p t_n v, \exp_p t_m v) \leq \|v\|_g |t_n - t_m|$ and then $\{\exp_p t_n v\}$ is a Cauchy sequence.

$\exists p_0 \in M, \lim_{n \rightarrow +\infty} \exp_p t_n v = p_0$, i.e. $\forall \delta > 0, \exists N$ such that $\exp_p t_n v \in B(p_0, \delta), \forall n \geq N$.

□

引理 7.3. 内容...

8 Cut locus 2

3 月 15 日 39 分 24 秒

定理 8.1. *Let (M, g) be a complete Riemannian manifold, then*

$$M = \exp_p(E(p)) \sqcup c(p).$$

定理 8.2. *Let (M, g) be a complete Riemannian manifold.*

Let $\gamma: [a, b] \rightarrow M$ be a normal geodesic with $p = \gamma(0)$, v

证明. Choose a sequence of parameters

$$a_1 > a_2 > a_3 > \cdots, \quad \lim_{i \rightarrow +\infty} a_i = a.$$

By completeness, $\exists v_i \in T_p M, \|v_i\| = 1$ such that

$$\gamma_i(t) = \exp_p tv_i, t \in [0, b_i]$$

is a shortest curve from p to $\gamma(a_i)$, where $b_i = d(p, \gamma(a_i))$.

Notice that $v_i \neq v$.

$$\lim_{i \rightarrow +\infty} p_i =$$

□

9 黎曼覆盖映射

10 Existence of shortest curves in given homotopy class

- isometry: 微分同胚, 度量等于拉回
-

3月15日 1小时26分15秒

定理 10.1. *Let (M, g) be compact.*

Then every homotopy class of closed curves in M contains a curve which is shortest in its homotopy class and a geodesic.

引理 10.2. *Let (M, g) be compact, $\exists \rho_0 > 0$ such that for any $\gamma_0, \gamma_1: S^1 \rightarrow M$ be closed curves with $d(\gamma_0(t), \gamma_1(t)) \leq \rho_0, \forall t \in S^1$ we have γ_0 and γ_1 are homotopic.*

引理 10.3. *A shortest curve in a homotopy class is geodesic.*

证明. Let $(\gamma_n)_{n \in \mathbb{N}}$ is a minimizing sequence for length in the homotopy class.

All are parametrized proportional to arc length.

We can find $0 = t_0 < t_1 < \dots < t_n < t_{n+1} = 2\pi$ with the property that

$$\text{Length}(\gamma_n |_{t_i, t_{i+1}}) \leq \frac{\rho_0}{2}$$

□

11 title

11.1 前情回顾

Riemannian Covering map

$\pi: (\tilde{M}, \pi^*g) \rightarrow (M, g)$ smooth map

locally Riemannian isometry

isometry $\varphi: (M, g_M) \rightarrow (N, g_N)$ is called an isometry if φ is diffeomorphism and $g_M = \varphi^*g_N$

locally isometry $\varphi: (M, g_M) \rightarrow (N, g_N)$ smooth map, $\forall p \in M \exists U \in \mathcal{P}$ such that $\varphi|_U: U \rightarrow \varphi(U)$ is an isometry 问题: 对 $\varphi(U)$ 有没有要求

locally Riemannian isometry $\varphi: (M, g_M) \rightarrow (N, g_N)$ smooth map, $\forall p \in M, d\varphi_p: T_p M \rightarrow T_{\varphi(p)} N$ is a linear isometry.

命题 11.1. *Let $\varphi: (M, g_M) \rightarrow (N, g_N)$ be a locally Riemannian isometry.*

- (1) φ maps geodesics to geodesics.
- (2) For any $\tilde{p}, \tilde{v} \in T_{\tilde{p}} M$, we have

$$\varphi \circ (\exp_{\tilde{p}} \tilde{v}) = \exp_{\varphi(\tilde{p})} (d\varphi_{\tilde{p}}(\tilde{v})).$$

$$\begin{array}{ccc} T_{\tilde{p}} M & \xrightarrow{d\varphi_{\tilde{p}}} & T_{\varphi(\tilde{p})} N \\ \downarrow & & \downarrow \\ M & \xrightarrow{\varphi} & N \end{array}$$

(3) φ is distance non-increasing.

$$\forall \tilde{p}, \tilde{q}, d_N(\varphi(\tilde{p}), \varphi(\tilde{q})) \leq d_M(\tilde{p}, \tilde{q})$$

(4) φ is bijective, then it is distance preserving.

定理 11.2. (M, g_M) complete Riemannian manifold, $p, q \in M$. Every homotopy class of paths from p to q contains a shortest curve.

证明. Assume that (M, g_M) complete $\implies (\tilde{M}, \pi^*g)$ is complete. □

命题 11.3. Let $\pi: (\tilde{M}, \tilde{g}) \rightarrow (M, g)$ is a Riemannian covering map, then (M, g) complete iff (\tilde{M}, \tilde{g}) complete.

证明.

(\tilde{M}, \tilde{g}) complete $\implies (M, g)$ complete $\forall \tilde{p} \in \tilde{M}, \tilde{v} \in T_{\tilde{p}}\tilde{M}, t \mapsto \exp_{\tilde{p}} t\tilde{v}$

$$p = \pi(\tilde{p}), v = d\pi(\tilde{p})(\tilde{v})$$

geodesic $t \mapsto \exp_p tv$ is defined on $[0, \infty)$

path lifting, $\exists \tilde{\gamma}$ a path in \tilde{M} such that $\tilde{\gamma}(0) = \tilde{p}, \pi \circ \tilde{\gamma} = \gamma$

$$\left. \frac{d\tilde{\gamma}}{dt} \right|_{t=0} = \tilde{v}$$

(M, g) complete $\implies (\tilde{M}, \tilde{g})$ complete $\forall p \in M, \forall v \in T_p M, t \mapsto \exp_p tv$ □

命题 11.4. Let $\pi: (\tilde{M}, \tilde{g}) \rightarrow (M, g)$ is a local Riemannian isometry. Suppose (\tilde{M}, \tilde{g}) complete. Then (M, g) is complete and π is a Riemannian covering map.

证明. (1) π is surjective.

$$\forall \tilde{p} \in \tilde{M}, p = \pi(\tilde{p}) \in M$$

$\forall q \in M, \exists$ a shortest geodesic γ from p to q .

Let $\tilde{\gamma}$ be the lifting of γ starting at $\tilde{p} = \tilde{\gamma}(0)$

$$\pi \circ \tilde{\gamma} = \gamma, q = \gamma(t_0), \pi \circ \tilde{\gamma}(t_0) = \gamma(t_0) = q$$

(2) evenly covered

$$p \in U, \pi^{-1}(U) = \bigsqcup_{\alpha \in \Lambda} \tilde{U}_\alpha$$

$\pi: \tilde{U}_\alpha \rightarrow U$ diffeomorphism

Normal ball $B(p, \varepsilon)$

$\tilde{U}_\alpha = B(\tilde{p}_\alpha, \varepsilon)$ metric ball

$$(a) \tilde{U}_\alpha \cap \tilde{U}_\beta = \emptyset, \forall \alpha \neq \beta$$

$$d(\tilde{p}_\alpha, \tilde{p}_\beta) \geq 2\varepsilon$$

$$(b) \pi^{-1}(U) = \bigcup_{\alpha \in \Lambda} \tilde{U}_\alpha$$

$$\bullet \forall \tilde{q} \in \tilde{U}_\alpha \text{ for some } \alpha \in \Lambda$$

\exists a geodesic $\tilde{\gamma}$ of length $< \varepsilon$ from

□

(U, x)

$$\frac{d^2 x^i(t)}{dt^2} + \Gamma_{jk}^i(x(t)) \frac{dx^j}{dt} \frac{dx^k}{dt} = 0, i = 1, \dots, n$$

12 能量泛函的变分 II

$$\begin{aligned}
 \frac{dE}{ds} &= \frac{1}{2} \int_a^b \frac{\partial}{\partial s} \left\langle \frac{\partial F}{\partial t}, \frac{\partial F}{\partial t} \right\rangle dt \\
 &= \int_a^b \left\langle \nabla_{\frac{\partial}{\partial s}} \frac{\partial F}{\partial t}, \frac{\partial F}{\partial t} \right\rangle dt \\
 &= \int_a^b \left\langle \nabla_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial s}, \frac{\partial F}{\partial t} \right\rangle dt \\
 &= \int_a^b \frac{\partial}{\partial t} \left\langle \frac{\partial F}{\partial s}, \frac{\partial F}{\partial t} \right\rangle dt - \int_a^b \left\langle \frac{\partial F}{\partial s}, \nabla_{\frac{\partial}{\partial t}} \frac{\partial F}{\partial t} \right\rangle dt \\
 E'(0) &= \langle V, T \rangle \Big|_a^b - \int_a^b \langle V, \nabla_T T \rangle dt
 \end{aligned}$$

$\frac{\partial F}{\partial t}$ 视作沿曲线 $F(t, \cdot)$ 的向量场

$\frac{\partial F}{\partial t}$ 视作沿 F 的向量场

3 月 29 日 1 小时 35 分 41 秒

12.1 Gauss 引理

3 月 29 日 1 小时 36 分 33 秒

12.2 第二变分公式

3 月 29 日 1 小时 51 分 30 秒

Chapter 3

联络和曲率

1 仿射联络

为什么要对向量场求导？因为欧氏空间中我们就已经在对向量场求导了。

比如浸入 $\gamma: I \rightarrow \mathbb{R}^3$ 的曲率, 我们选择弧长参数, $\gamma'(s)$ 是一个沿 γ 的单位长的切向量场, 我们继续对它求导, 这就是对向量场的求导, 得到 $\gamma''(s)$, 我们把这玩意的模长叫做曲率, 用来刻画曲线的弯曲程度.

2 拉回丛及诱导联络

定义 2.1. 拉回丛

例子 2.2. 沿曲线的向量场

定义 2.3. 设 $\varphi: N \rightarrow M$ 是光滑映射. 称 $V: N \rightarrow TM$ 是沿 φ 的向量场, 如果 $V(x) \in T_{\varphi(x)}M$.

命题 2.4. 两个概念是一致的.

定义 2.5. 诱导联络

命题 2.6. 诱导联络在基下的计算方式.

2.1 沿曲线的协变导数

定义 2.7. 给定 C^∞ 曲线 $c: [a, b] \rightarrow M$, 称 $V: [a, b] \rightarrow M$ 是沿 c 的向量场, 如果 $V(t) \in T_{c(t)}M$. 我们称 V 是光滑的, 如果对任意的 $f \in C^\infty(M)$, 函数 $V(t)f$ 是光滑的. 记沿 c 的光滑向量场全体为 $\Gamma(TM|_c)$, 它显然是 $C^\infty([a, b])$ 模.

在一个坐标卡 (U, x) 中, $V(t)$ 能够被表达为

$$V(t) = V^i(t) \frac{\partial}{\partial x^i} \Big|_{c(t)}.$$

容易验证 V 是光滑的 $\iff V^i(t)$ 是光滑的, $1 \leq i \leq n$.

命题 2.8. 设 M 是光滑流形, ∇ 是其上的仿射联络. 存在唯一的 $\frac{D}{dt}: \Gamma(TM|_c) \rightarrow \Gamma(TM|_c)$ 满足

$$(1) \frac{D(V+W)}{dt} = \frac{DV}{dt} + \frac{DW}{dt}$$

$$(2) \frac{D(fV)}{dt} = \frac{df}{dt}V + f \frac{DV}{dt}, \forall f \in C^\infty([a, b])$$

$$(3) \text{ 如果存在 } X \in \mathfrak{X}(M) \text{ 使得 } V(t) = X(c(t)), \text{ 那么 } \frac{DV}{dt} = \nabla_{c'(t)}X.$$

2.2 诱导联络

(M, ∇)
 $\frac{DV}{dt}$, V vector field along a curve c
 induced connection

$c: (-\varepsilon, \varepsilon) \rightarrow M$

Let $\varphi: N \rightarrow M$ C^∞ map.

A C^∞ vector field along φ .

$x \in N \mapsto V(x) \in T_{\varphi(x)}M$

$\varphi(x) \in M$, frame field E_i in a neighborhood

$V(x) = \sum V^i(x)E_i(\varphi(x))$ 其中 V^i 看作 N 上的函数

Given $u \in T_xN$, $\tilde{\nabla}_u V = \sum u(V^i)E_i(\varphi(x)) + V^i(x)\nabla_{d\varphi(x)(u)}E_i(\varphi(x))$

induced connection

更多内容可参考刘老师 18 年的某次作业

3 平行移动

上节的铺垫使得我们能够讨论平行性.

定义 3.1. 称沿曲线 $c: [a, b] \rightarrow M$ 的向量场 V 是平行的如果 $\frac{DV}{dt} \equiv 0$.

3月22日第二段 8分8秒

给定一个切向量 $V_a \in T_{c(a)}M$, 假使能够找到一个沿 c 的平行切向量场 V 满足 $V(a) = V_a$, 我们便可认为 V_a 沿曲线 c 平行地移动到了 $c(t)$ 处成为 $V(t)$.

我们问 V 是否存在? 在多大的范围内存在? 这等价于去解方程 $\frac{DV}{dt} = 0$.

回忆测地线方程是一个非线性 ODE, 因此我们只有解的局部存在性. 而这里 $\frac{DV}{dt} = 0$ 是一个线性方程, 从而可保证解整体存在.

命题 3.2. 设 $c: [a, b] \rightarrow M$ 是光滑曲线. 设 $V_0 \in T_{c(t_0)}M$, $t_0 \in [a, b]$, 那么存在唯一的沿 c 平行的向量场 V 使得 $V(t_0) = V_0$.

证明. $c(I) \subset (U, x)$

□

3月22日第二段 14分35秒

命题 3.3. Let c be a C^∞ curve with $c(0) = p, c'(0) = X(p)$

Let $Y \in \Gamma(TM)$

$$\text{Then } \nabla_{X(p)} Y = \lim_{h \rightarrow 0} \frac{P_{c,0,h}^{(c)}(Y(c(h))) - Y(c(0))}{h}$$

证明. Let V_1, \dots, V_n be parallel vector fields along c which is linearly independent.

$Y(c(t)) = f^i(t)V_i(t)$, 这是一件非常方便的事情

$$\begin{aligned} RHS &= \lim_{h \rightarrow 0} \frac{f_i(h)V_i(0) - f_i(0)V_i(0)}{h} = \left. \frac{df^i}{dh} \right|_{h=0} V_i(0) \\ &= \left. \frac{D}{dt} (f^i(t)V_i(t)) \right|_{t=0} \\ &= \left. \frac{DY}{dt} \right|_{t=0} = \nabla_{\frac{dc}{dt}(0)} Y = \nabla_{X(p)} Y \end{aligned}$$

□

4 张量场的协变导数

本节我们从切丛上的一个联络出发, 定义张量丛上的一个联络.

定理 4.1. 设 M 是光滑流形, ∇ 是其上的仿射联络, 那么存在唯一的映射

$$\nabla: \Gamma(TM) \times \Gamma\left(\bigotimes^{r,s} TM\right) \rightarrow \Gamma\left(\bigotimes^{r,s} TM\right)$$

满足

- (1) $\nabla_{fX+gY}A = f\nabla_XA + g\nabla_YA$
- (2) $\nabla_X(A_1 + A_2) = \nabla_XA_1 + \nabla_XA_2$
- (3) $\nabla_X(fA) = (Xf)A + f\nabla_XA$
- (4) 当 $A \in C^\infty(M)$ 或 $\Gamma(TM)$ 时, ∇ 与给定的仿射联络一致.
- (5) $\nabla_X(A_1 \otimes A_2) = (\nabla_XA_1) \otimes A_2 + A_1 \otimes \nabla_XA_2$
- (6) $C(\nabla_XA) = \nabla_X(CA)$, 其中 $C: \Gamma(\bigotimes^{r,s} TM) \rightarrow \Gamma(\bigotimes^{r-1,s-1} TM)$

证明. $A \in \Gamma(\bigotimes^{r,s} TM)$

$$A = A_{j_1 j_2 \dots j_s}^{i_1 i_2 \dots i_r} Y_{i_1} \otimes Y_{i_2} \otimes \dots \otimes Y_{i_r} \otimes \omega^{j_1} \otimes \dots \otimes \omega^{j_s}$$

$$\begin{aligned} \nabla_X A &= \sum \nabla_X \\ &= \sum X(A_{j_1 \dots j_s}^{i_1 \dots i_r}) Y_{i_1} \end{aligned}$$

线性, Leibniz

唯一的问题是如何对微分 1 形式求导

$$\omega \in \Omega^1(M) = \Gamma(T^*M)$$

$$\nabla_X \omega?$$

$$\forall Y \in \Gamma(TM), \omega(Y) \in C^\infty(TM)$$

$$X(\omega(Y)) = \nabla_X(\omega(Y)) = \nabla_X(C(\omega \otimes Y)) = C(\nabla_X(\omega \otimes Y))$$

$$C(\nabla_X \omega \otimes Y + \omega \otimes \nabla_X Y)$$

$$\nabla_X(\omega)Y + \omega(\nabla_X Y)$$

$$(\nabla_X \omega) = X(\omega(Y)) - \omega(\nabla_X Y)$$

$$\implies \text{uniqueness}$$

□

注记. (1) is a consequence of the other assumptions.

不是那么令人惊讶, 这是说在这里是多余的, 而不是在仿射联络的最初定义中也是多余的

$$\forall X, Y, Z \in \Gamma(TM)$$

$$f, g \in C^\infty(TM), \omega \in \Gamma(T^*M)$$

证明. $(fX + gY)\omega(Z) = \nabla_{fX+gY}\omega(Z) + \omega(\nabla_{fX+gY}Z)$

$$= fX(\omega(Z)) + gY(\omega(Z))$$

□

推论 4.2. $\forall A \in \Gamma(\bigotimes^{r,s} TM), \omega_\alpha \in \Gamma(T^*M), \alpha = 1, 2, \dots, r, Y_j \in \Gamma(TM), j = 1, \dots, s$

We have $(\nabla_X A)(\omega_1, \dots, \omega_s; Y_1, \dots, Y_s)$

$$= A(\omega_1, \dots, \omega_r, Y_1, \dots, Y_s)$$

locality

$\nabla_X A(p)$ only depends on X at p and Y in $U \ni p$.

(M, ∇)

$\varphi: V \rightarrow W$ isomorphism

$\varphi^*: W^* \rightarrow V^*$ isomorphism, $\alpha \mapsto \varphi^*(\alpha)$

$\forall v \in V, \varphi^*(\alpha)(v) := \alpha(\varphi(v))$

$P_{c,0,t}: T_{c(0)}M \rightarrow T_{c(t)}M$

$$\longrightarrow \tilde{P}_{c,0,t}: \bigotimes^{r,s} T_{c(0)}M \rightarrow \bigotimes^{r,s} T_{c(t)}M$$

$$v_1 \otimes \dots \otimes v_r \otimes \omega^1 \otimes \dots \otimes \omega^r \mapsto P_{c,0,t}(v_1) \otimes \dots \otimes$$

Define $\nabla_{X(p)} A := \lim_{h \rightarrow 0} \frac{\tilde{P}}{h}$

定义 4.3. A tensor field is called parallel if $\nabla_X A = 0, \forall X \in \Gamma(TM)$.

$$\begin{aligned} c(t) &= (c^1(t), \dots, c^n(t)) \\ \frac{Dc'(t)}{dt} &= \frac{D}{dt} \left(\frac{dc^i(t)}{dt} \frac{\partial}{\partial x^i} \right) \\ &= \frac{d^2 c^i(t)}{dt^2} \frac{\partial}{\partial x^i} + \frac{dc^i(t)}{dt} \nabla_{\frac{dc^j}{dt} \frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^i} \\ &= \left(\frac{d^2 c^k(t)}{dt^2} \right) \frac{\partial}{\partial x^k} \end{aligned}$$

5 Levi-Civita 联络

定义 5.1. 称仿射联络 ∇ 是 (M, g) 上的 Levi-Civita 联络如果 $\nabla_X Y - \nabla_Y X = [X, Y]$ 且 $\nabla g = 0$.

命题 5.2. ∇ 是无挠的 $\iff \Gamma_{ij}^k = \Gamma_{ji}^k$.

证明. 容易看出 $\Gamma_{ij}^k = \Gamma_{ji}^k \iff \nabla_{\partial_i} \partial_j = \nabla_{\partial_j} \partial_i$. 那么

$$\begin{aligned} \nabla_X Y &= \nabla_{X^i \partial_i} (Y^j \partial_j) \\ &= X^i \frac{\partial Y_j}{\partial x^i} \frac{\partial}{\partial x^j} + X^i Y^j \nabla_{\partial_i} \partial_j \\ &= \nabla_Y X + [X, Y]. \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial t} R_{ijkl} &= \Delta R_{ijkl} + 2(B_{ijk}l - B_{ijlk} - B_{iljk} + B_{ikjl}) \\ &\quad - g^{pq} R_{pjkl} R_{qi} + R_{ipkl} R_{qj} + R_{ijpl} R_{qk} + R_{ijkp} R_{ql} \end{aligned}$$

□

命题 5.3. ∇ 是度量相容的 $\iff g_{ij,l} = g_{ik} \Gamma_{jl}^k + g_{kj} \Gamma_{il}^k$.

证明.

□

定理 5.4 (黎曼几何基本定理). 任意黎曼流形 (M, g) 上存在唯一的 Levi-Civita 联络.

局部坐标下的证明. 假定存在性. 轮换一下就能说明 $\Gamma_{ij}^k = \frac{1}{2} g^{kl} (g_{il,j} + g_{jl,i} - g_{ij,l})$.

□

不用坐标的证明. Suppose existence.

Given $X, Y \in \Gamma(TM)$, we can determine $\nabla_X Y$ by determine $\langle \nabla_X Y, Z \rangle$ for any $Z \in \Gamma(TM)$.

$$\begin{aligned} \langle \nabla_X Y, Z \rangle &\stackrel{(2)}{=} X \langle Y, Z \rangle - \langle Y, \nabla_X Z \rangle \\ &\stackrel{(1)}{=} X \langle Y, Z \rangle - \langle Y, \nabla_Z X + [X, Z] \rangle \\ &= X \langle Y, Z \rangle - \langle Y, [X, Z] \rangle - \langle Y, \nabla_Z X \rangle \\ &\stackrel{(2)}{=} X \langle Y, Z \rangle - \langle Y, [X, Z] \rangle - Z \langle Y, X \rangle + \langle \nabla_Z Y, X \rangle \\ &\stackrel{(1)}{=} X \langle Y, Z \rangle - \langle Y, [X, Z] \rangle - Z \langle Y, X \rangle + \langle \nabla_Y Z + [Z, Y], X \rangle \\ &= X \langle Y, Z \rangle - \langle Y, [X, Z] \rangle - Z \langle Y, X \rangle + \langle X, [Z, Y] \rangle + \langle \nabla_Y Z, X \rangle \\ &\stackrel{(2)}{=} X \langle Y, Z \rangle - \langle Y, [X, Z] \rangle - Z \langle Y, X \rangle + \langle X, [Z, Y] \rangle + Y \langle Z, X \rangle - \langle Z, \nabla_Y X \rangle \\ &\stackrel{(1)}{=} X \langle Y, Z \rangle - \langle Y, [X, Z] \rangle - Z \langle Y, X \rangle + \langle X, [Z, Y] \rangle + Y \langle Z, X \rangle - \langle Z, \nabla_X Y + [Y, X] \rangle \\ 2 \langle \nabla_X Y, Z \rangle &= X \langle Y, Z \rangle + Y \langle Z, X \rangle - Z \langle X, Y \rangle - \langle X, [Y, Z] \rangle + \langle Y, [Z, X] \rangle + \langle Z, [X, Y] \rangle \end{aligned}$$

□

引理 5.5. 设 (M, g) 是黎曼流形, ∇ 是其上与 g 相容的联络. 设 $c: (a, b) \rightarrow M$ 是光滑曲线, $\frac{D}{dt}$ 是 ∇ 诱导的沿曲线的协变导数. 设 $V(t), W(t)$ 是沿 c 的光滑曲线, 那么

$$\frac{d}{dt} \langle V(t), W(t) \rangle = \left\langle \frac{DV}{dt}(t), W(t) \right\rangle + \left\langle V(t), \frac{DW}{dt}(t) \right\rangle.$$

证明. 设在坐标邻域 (U, x) 中 $V(t) = V^i(t) \frac{\partial}{\partial x^i} \Big|_{c(t)}$, $W(t) = W^j(t) \frac{\partial}{\partial x^j} \Big|_{c(t)}$, 那么

$$\begin{aligned}
 \text{LHS} &= \frac{d}{dt} \left(V^i(t) W^j(t) \left\langle \frac{\partial}{\partial x^i} \Big|_{c(t)}, \frac{\partial}{\partial x^j} \Big|_{c(t)} \right\rangle \right) \\
 &= \left\langle \frac{dV^i}{dt}(t) \frac{\partial}{\partial x^i} \Big|_{c(t)}, W(t) \right\rangle + \left\langle V(t), \frac{dW^j}{dt}(t) \frac{\partial}{\partial x^j} \Big|_{c(t)} \right\rangle + V^i(t) W^j(t) \frac{d}{dt} \left\langle \frac{\partial}{\partial x^i} \Big|_{c(t)}, \frac{\partial}{\partial x^j} \Big|_{c(t)} \right\rangle \\
 &= \left\langle \frac{dV^i}{dt}(t) \frac{\partial}{\partial x^i} \Big|_{c(t)}, W(t) \right\rangle + \left\langle V(t), \frac{dW^j}{dt}(t) \frac{\partial}{\partial x^j} \Big|_{c(t)} \right\rangle + V^i(t) W^j(t) \frac{d}{dt} g \left(\frac{\partial}{\partial x^i} \Big|_{c(t)}, \frac{\partial}{\partial x^j} \Big|_{c(t)} \right) \\
 &= \left\langle \frac{dV^i}{dt}(t) \frac{\partial}{\partial x^i} \Big|_{c(t)}, W(t) \right\rangle + \left\langle V(t), \frac{dW^j}{dt}(t) \frac{\partial}{\partial x^j} \Big|_{c(t)} \right\rangle + V^i(t) W^j(t) c'(t) g \left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right) \\
 &= \left\langle \frac{dV^i}{dt}(t) \frac{\partial}{\partial x^i} \Big|_{c(t)}, W(t) \right\rangle + \left\langle V(t), \frac{dW^j}{dt}(t) \frac{\partial}{\partial x^j} \Big|_{c(t)} \right\rangle + V^i(t) W^j(t) \nabla_{c'(t)} g \left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right) \\
 &= \left\langle \frac{DV}{dt}, W \right\rangle + \left\langle V, \frac{DW}{dt} \right\rangle
 \end{aligned}$$

□

注记.

命题 5.6. 设 (M, g) 是黎曼流形, ∇ 是其上的仿射联络. 那么 ∇ 与 g 相容当且仅当任意平行移动是等距同构.

证明. $c: [a, b] \rightarrow M$ curve

$$\mathcal{P}_{c,a,t}: T_{c(a)}M \rightarrow T_{c(t)}M$$

-
- 任意 $X, Y, Z \in \Gamma(TM), \forall p \in M$

□

命题 5.7. 设 ∇ 是 M 上的无挠联络. 设 $s: \mathbb{R}^2 \rightarrow M \in C^\infty$, V 是沿 s 的光滑向量场. 那么

$$\tilde{\nabla}_{\frac{\partial}{\partial x}} s_* \frac{\partial}{\partial y} = \tilde{\nabla}_{\frac{\partial}{\partial y}} s_* \frac{\partial}{\partial x}.$$

证明. 直接在局部坐标下计算.

□

6 能量泛函的第二变分公式与曲率张量

7 协变微分与 Ricci 恒等式

4 月 1 日 1 小时 23 分 16 秒

7.1 局部坐标下的协变微分

8 音乐同构

$$\flat: T_p M \longrightarrow T_p^* M, \quad X \longmapsto \flat X, \quad \flat X(Y) = g(X, Y).$$

$$\sharp: T_p^* M \longrightarrow T_p M, \quad \omega \longmapsto \sharp \omega, \quad g(\sharp \omega, Y) = \omega(Y).$$

9 算符

9.1 Hessian

9.2 散度

9.3 梯度

•

9.4 拉普拉斯

10 Bianchi 恒等式

- 第一 Bianchi 恒等式的 global 版本、证明和局部版本
- 第二 Bianchi 恒等式的 global 版本、证明和局部版本

命题 10.1. 设 M 是光滑流形, ∇ 是其上无挠的仿射联络, R 是相应的曲率张量. 那么对于任意 $X, Y, Z, W \in \Gamma(TM)$, 我们有

(1) (第一 Bianchi 恒等式) $R(X, Y)Z + R(Y, Z)X + R(Z, X)Y = 0.$

(2) (第二 Bianchi 恒等式) $(\nabla_X R)(Y, Z)W$

11 Riemann 曲率张量

12 截面曲率

13 高斯绝妙定理

14 Ricci 曲率

15 数量曲率

16 Bochner 公式

17 测地曲率

18 Gauss-Bonnet 公式

定理 18.1. 设 M 是紧的二维黎曼流形, 其边界 ∂M 光滑, 则

$$\int_M K dA + \int_{\partial M} k_g ds = 2\pi\chi(M).$$

Chapter 4

Jacobi 场

1 Jacobi 场

定义 1.1. 设 $\gamma: [a, b] \rightarrow M$ 是一条测地线. 对于 $t_0, t_1 \in [a, b]$, 如果存在沿 γ 的不恒为零的 *Jacobi* 场 $U(t)$, 满足 $U(t_0) = U(t_1) = 0$, 则称 t_0, t_1 是沿 γ 的共轭值. 将所有这样的 *Jacobi* 场与恒为零的向量场所构成的线性空间的维数称作 t_0 和 t_1 作为共轭值的重数. 称 $\gamma(t_0)$ 和 $\gamma(t_1)$ 为沿 γ 的共轭点.

2 Morse 指标定理

3 Cartan-Hadamard 定理

4 空间形式

定义 4.1. 称常截面曲率的完备黎曼流形为空间型.

引理 4.2. 内容...

定理 4.3. 设 (M_i^n, g_i) 是单连通、截面曲率为 c 的空间型. 设 $p_i \in M_i$, $\{e_i^1, \dots, e_i^n\}$ 是 $T_{p_i}M_i$ 的标准正交基, 那么存在唯一的保距映射 $\varphi: M_1 \rightarrow M_2$ 使得 $\varphi(p_1) = p_2, \varphi_{*,p}(e_1^j) = e_2^j$.

5 单连通空间形式的等距群

5.1 \mathbb{R}^n

命题 5.1. $Iso(\mathbb{R}^n) \cong T(n) \rtimes O(n)$.

证明. 假设 $f \in Iso(\mathbb{R}^n)$ 满足 $f(0) = 0$, 否则考虑 $\tilde{f} = f - f(0)$.

(1) f 保持内积. 因为 f 保持距离, 所以对任意 $x, y \in \mathbb{R}^n$, 有

$$\|f(x) - f(y)\|^2 = \|x - y\|^2 \implies \langle f(x), f(y) \rangle = \langle x, y \rangle.$$

(2) f 是线性的.

$$\bullet \|f(ax) - af(x)\|^2 = \|f(ax)\|^2 + \|af(x)\|^2 - 2\langle f(ax), af(x) \rangle = \|ax\|^2 + \|ax\|^2 - 2\|ax\|^2 = 0.$$

$$\bullet \|f(x+y) - f(x) - f(y)\|^2 \xrightarrow{\text{展开}} \dots \xrightarrow{\text{脱}f} \dots \xrightarrow{\text{合并}} \|x+y-x-y\|^2 = 0.$$

(3) $f \in O(n)$.

□

注记. 证明了稍稍强一点的事: 等距 \implies 双射.

5.2 \mathbb{S}^n

命题 5.2. $Iso(\mathbb{S}^n) \cong O(n+1)$.

证明. <https://math.stackexchange.com/questions/130193/isometries-of-mathbbbn>

□

5.3 \mathbb{H}^n

6 Killing-Hopf 定理

7 距离函数

Chapter 5

比较定理

1 Sturm 比较定理

2 Rauch 比较定理

3 Hessian 比较定理

4 Laplacian 比较定理

5 体积比较定理

Chapter 6

规范理论